

# Normalized Solutions for a Planar Schrödinger-Poisson System with Inhomogeneous Attractive Interactions

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# Abstract

This paper is devoted to the normalized solutions of a planar  $L^2$ -critical Schrödinger-Poisson system with an external potential  $V(x) = |x|^2$  and inhomogeneous attractive interactions  $K(x) \in (0,1)$ . Applying the constraint variational method, we prove that the normalized solutions exist if and only if the interaction strength *a* satisfies  $a \in (0, a^*) := \|Q\|_{L^2(\mathbb{R}^2)}^2$ , where *Q* is the unique positive solution of  $\Delta u - u + u^3 = 0$  in  $\mathbb{R}^2$ . Particularly, the refined limiting behavior of positive minimizers is also analyzed as  $a \nearrow a^*$ .

# **Subject Areas**

Mathematics, Partial Differential Equation

# **Keywords**

Schrödinger-Poisson System, Logarithmic Convolution, Inhomogeneous Attractive Interaction, Normalized Solution

# **1. Introduction**

In this paper, we study the following inhomogeneous elliptic equation with a power potential and a logarithmic convolution potential

$$-\Delta u + (|x|^2 - \mu)u + (\ln|x| * u^2)u = aK(x)|u|^2 u \text{ in } \mathbb{R}^2,$$
(1.1)

where  $\mu \in \mathbb{R}$  is an uncertain Lagrange constant, a > 0 denotes the strength of attractive interactions, and K(x) > 0 gives the spatially inhomogeneous attractive interactions. Under the standing wave ansatz  $\psi(x,t) = e^{i\mu t}u(x)$ , where *i* is

the imaginary unit, it is well known that (1.1) can be obtained from the timedependent Schrödinger-Poisson system

$$\begin{aligned} &\left[i\psi_t - \Delta\psi + \left|x\right|^2 \psi + \lambda\omega\psi = aK(x)\left|\psi\right|^2 \psi & \text{in } \mathbb{R}^2 \times \mathbb{R}, \\ &\Delta\omega = \left|\psi\right|^2 & \text{in } \mathbb{R}^2 \times \mathbb{R}, \end{aligned}$$

where  $\psi : \mathbb{R}^2 \times \mathbb{R} \to \mathbb{C}$  is the time-dependent wave function and  $\lambda \in \mathbb{R}$  is a parameter. The function  $\omega$  represents an internal potential for a nonlocal self-interaction of the wave function  $\psi$ , and the nonlinear term  $|\psi|^2 \psi$  is frequently used to model the interaction among particles [1]-[3]. In the past several decades, this system, as a cross-disciplinary model bridging quantum mechanics and classical electromagnetism, has garnered great attention owing to its physical relevance. It originates from quantum mechanics [4]-[9] and especially semiconductor physics [10] [11]. We would like to mention the results [12]-[15] for normalized solutions of inhomogeneous elliptic equations, and [15]-[18] with references therein for the Schrödinger-Poisson systems.

In order to investigate the normalized solutions of (1.1), we define the energy functional

$$E_{a}(u) \coloneqq \frac{1}{2} \int_{\mathbb{R}^{2}} \left[ \left| \nabla u(x) \right|^{2} + |x|^{2} u^{2}(x) \right] dx + \frac{1}{4} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln|x - y| u^{2}(x) u^{2}(y) dx dy - \frac{a}{4} \int_{\mathbb{R}^{2}} K(x) u^{4}(x) dx.$$
(1.2)

Due to the power potential term and the logarithmic convolution term,  $E_a$  is not well defined on  $H^1(\mathbb{R}^2)$ . Stimulated by [14], we consider the space X satisfying

$$X := \left\{ u \in H^{1}(\mathbb{R}^{2}) : ||u||_{*} := \left( \int_{\mathbb{R}^{2}} |x|^{2} u^{2}(x) dx \right)^{\frac{1}{2}} < \infty \right\}$$

with the associated norm

$$||u||_{X} := \left\{ \int_{\mathbb{R}^{2}} \left[ |\nabla u|^{2} + (1 + |x|^{2})u^{2}(x) \right] dx \right\}^{\frac{1}{2}}, \ u \in X$$

Recall from ([19], Lemma 3.1) that for any  $p \in [2, \infty)$ ,

X is compactly embedded into  $L^p(\mathbb{R}^2)$ . (1.3)

As performed in [20], we decompose the logarithmic convolution term as below:

$$F_1(u) \coloneqq \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln\left(1 + |x - y|\right) u^2(x) u^2(y) dxdy,$$
  
$$F_2(u) \coloneqq \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln\left(1 + \frac{1}{|x - y|}\right) u^2(x) u^2(y) dxdy,$$

and

$$F_1(u) - F_2(u) = \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln |x - y| u^2(x) u^2(y) dx dy.$$

In what follows, we use  $\|\cdot\|_p$  to denote the standard Lebesgue norm on  $L^p(\mathbb{R}^2)$ . Since

$$\ln(1+|x-y|) \le |x-y| \le |x|+|y|, \ x, y \in \mathbb{R}^2,$$

cwe derive from the Hölder inequality that

$$F_{1}(u) \leq \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \left( |x| + |y| \right) u^{2}(x) u^{2}(y) dx dy \leq 2 \left\| u \right\|_{2}^{3} \left\| u \right\|_{*}.$$
 (1.4)

From the fact that  $0 < \ln(1+r) < r$  holds for all r > 0 again, we can deduce from the Hardy-Littlewood-Sobolev inequality (cf. [21]):

$$\int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \frac{|u(x)| |v(y)|}{|x-y|} dx dy \le C \|u\|_{\frac{4}{3}} \|u\|_{\frac{4}{3}}, \ u, v \in L^{\frac{4}{3}}(\mathbb{R}^2),$$
(1.5)

that there exists a constant C > 0 such that

$$F_{2}(u) \leq \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \frac{u^{2}(x)u^{2}(y)}{|x-y|} dx dy \leq C \|u\|_{\frac{8}{3}}^{4}, \ u \in L^{\frac{8}{3}}(\mathbb{R}^{2}).$$
(1.6)

It follows from (1.4) and (1.6) that  $\int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln |x-y| u^2(x) u^2(y) dx dy$  is well defined on X.

Throughout the paper, we assume that the inhomogeneous attractive interactions K(x) satisfy that

$$0 < K(x) \le 1$$
 and  $K(0) = \sup_{x \in \mathbb{R}^2} K(x) = 1.$  (1.7)

Hence  $E_a$  is well defined on X. In the following we focus on studying the minimizers of the constraint variational problem:

$$e(a) \coloneqq \inf_{u \in S} E_a(u), \tag{1.8}$$

where the manifold S is defined by

$$S := \left\{ u \in X : \int_{\mathbb{R}^2} u^2(x) \, \mathrm{d}x = 1 \right\}.$$

The main purpose of this paper is to prove the existence, nonexistence and the refined limiting behavior of minimizers for e(a). The proof is closely related to the unique (up to translations) positive solution Q(x) = Q(|x|) of the following elliptic equation (cf. [22] [23]):

$$-\Delta u + u = u^3, \ u \in H^1(\mathbb{R}^2).$$

$$(1.9)$$

Note from [23] that the function Q(x) satisfies exponential decay in the sense that

$$Q(|x|), |\nabla Q(|x|)| = O\left(|x|^{-\frac{1}{2}} e^{-|x|}\right) \text{ as } |x| \to \infty.$$
(1.10)

In addition, we also need the following Gagliardo-Nirenberg inequality (cf. [24]):

$$\int_{\mathbb{R}^{2}} |u(x)|^{4} dx \leq \frac{2}{\|Q\|_{2}^{2}} \int_{\mathbb{R}^{2}} |\nabla u(x)|^{2} dx \int_{\mathbb{R}^{2}} |u(x)|^{2} dx, \ u \in H^{1}(\mathbb{R}^{2}),$$
(1.11)

where the equality is achieved at u(x) = Q(|x|). We can derive from (1.9) and (1.11) that

$$\int_{\mathbb{R}^{2}} \left| \nabla Q(x) \right|^{2} dx = \int_{\mathbb{R}^{2}} Q^{2}(x) dx = \frac{1}{2} \int_{\mathbb{R}^{2}} Q^{4}(x) dx, \qquad (1.12)$$

Applying the above facts, we can establish the existence and nonexistence of minimizers for e(a).

**Theorem 1.1.** Let Q(x) = Q(|x|) be the unique positive solution of (1.9) and  $a^* := \|Q\|_2^2$ .

1) If  $a \in (0, a^*)$ , then there exists at least one minimizer of e(a);

2) If  $a \in (a^*, \infty)$ , then there is no minimizer of e(a) and  $e(a) = -\infty$ ;

3) If  $a = a^*$  and  $1 - K(x) = O(|x|^2)$  as  $x \to 0$ , then there is no minimizer of e(a) and  $e(a) = -\infty$ .

Moreover, there holds  $\lim_{a \neq a} e(a) = -\infty$  when  $1 - K(x) = O(|x|^2)$  as  $x \to 0$ .

Suppose that  $u_a$  is a minimizer of e(a) for  $a \in (0, a^*)$ , then according to the variational theory,  $u_a$  satisfies the following Euler-Lagrange equation:

$$-\Delta u_{a} + |x|^{2} u_{a} + \int_{\mathbb{R}^{2}} \ln|x - y| u_{a}^{2}(y) dy u_{a} = \mu_{a} u_{a} + aK(x) |u_{a}|^{2} u_{a} \quad \text{in } \mathbb{R}^{2},$$
(1.13)

where  $\mu_a \in \mathbb{R}$  denotes the Lagrange multiplier and satisfies

$$u_{a} = 2e(a) + \frac{1}{2} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln|x - y| u_{a}^{2}(x) u_{a}^{2}(y) dx dy - \frac{a}{2} \int_{\mathbb{R}^{2}} K(x) u_{a}^{4} dx.$$
(1.14)

That is,  $u_a$  is a normalized solution of (1.1). Noticing  $E_a(|u_a|) = E_a(u_a)$ , we get that  $|u_a|$  is also a minimizer of e(a). Together with the strong maximum principle, we next mainly discuss the limiting behavior of positive minimizers.

**Theorem 1.2.** Assume that  $u_a$  is a positive minimizer of e(a) for  $a \in (0, a^*)$  and  $1-K(x) = O(|x|^2)$  as  $x \to 0$ . Then

$$\lim_{a \nearrow a^{*}} 2\sqrt{\frac{a^{*}-a}{a^{*}}} u_{a} \left( 2\sqrt{\frac{a^{*}-a}{a^{*}}} x + x_{a} \right) = Q(x) \text{ in } X,$$

where  $x_a$  is the unique global maximum point of  $u_a$  as  $a \nearrow a^*$ .

The proof of Theorem 1.2 requires a series of analysis. We have to overcome the sign-changing property of the logarithmic convolution term. We shall derive the following crucial estimate: there exists a constant C > 0 such that for any  $x \in \mathbb{R}^2$  and for all  $a \in (0, a^*)$ , there holds

$$\int_{\mathbb{R}^2} \ln\left(1 + \frac{1}{|x-y|}\right) v_a^2(y) \, \mathrm{d}y \le C,$$

where  $v_a$  is a suitable scaled function of the minimizer  $u_a$ .

We organize the next of this paper as follows. In Section 2, we prove Theorem 1.1 on the existence and nonexistence of minimizers for e(a). In Section 3, we prove Theorem 1.2 on the refined limiting behavior of positive minimizers for e(a) as  $a \nearrow a^*$ .

## 2. Existence and Nonexistence of Minimizers

In this section, we shall complete the proof of Theorem 1.1 by applying the Gagliardo-Nirenberg inequalities and the properties of Q(x).

**Proof of Theorem 1.1.** 1). For any  $p \ge 2$  and  $u \in H^1(\mathbb{R}^2)$ , there results the Gagliardo-Nirenberg inequality (cf. [24]):

$$\left\|u\right\|_{p} \leq \left(\frac{p}{2\left\|Q_{p}\right\|_{2}^{p-2}}\right)^{\frac{1}{p}} \left(\int_{\mathbb{R}^{2}} \left|\nabla u\right|^{2} \mathrm{d}x\right)^{\frac{p-2}{2p}} \left(\int_{\mathbb{R}^{2}} \left|u\right|^{2} \mathrm{d}x\right)^{\frac{1}{p}},$$
(2.1)

where  $Q_p$  is the positive ground state solution of the following elliptic equation

$$-\frac{p-2}{2}\Delta u+u=u^{p-1}, \ u\in H^1(\mathbb{R}^2).$$

By (1.6) and (2.1), we derive that there exists a constant C > 0 such that

$$F_2(u) \le C\left(\int_{\mathbb{R}^2} \left|\nabla u\right|^2 \mathrm{d}x\right)^{\frac{1}{2}}, \ u \in S.$$
(2.2)

Under the assumption (1.7), we deduce from (1.11) that

$$\int_{\mathbb{R}^2} K(x) u^4 \mathrm{d}x \le \int_{\mathbb{R}^2} u^4 \mathrm{d}x \le \frac{2}{a^*} \int_{\mathbb{R}^2} |\nabla u|^2 \,\mathrm{d}x, \ u \in S.$$
(2.3)

Notice that  $F_1(u) \ge 0$ , we infer from (2.2) and (2.3) that for  $u \in S$ ,

$$E_{a}(u) \geq \left(\frac{1}{2} - \frac{a}{2a^{*}}\right) \int_{\mathbb{R}^{2}} |\nabla u|^{2} dx + \frac{1}{2} \int_{\mathbb{R}^{2}} |x|^{2} u^{2} dx - C\left(\int_{\mathbb{R}^{2}} |\nabla u|^{2} dx\right)^{\frac{1}{2}}, \quad (2.4)$$

which implies that  $E_a(u)$  is bounded from below on S when  $a \in (0, a^*)$ .

Letting  $\{u_n\} \subset S$  be a minimizing sequence of e(a) for  $a \in (0, a^*)$ , we can know from (2.4) that  $\int_{\mathbb{R}^2} |\nabla u_n|^2 dx$  and  $\int_{\mathbb{R}^2} |x|^2 u_n^2 dx$  are bounded uniformly with respect to n. Since  $\int_{\mathbb{R}^2} u_n^2 dx = 1$ , we then obtain that  $\{u_n\}$  is bounded uniformly in X. By (1.3), there exists a function  $u \in X$  such that

 $u_n \rightarrow u$  in X and  $u_n \rightarrow u$  in  $L^p(\mathbb{R}^2)$  for  $p \in [2,\infty)$ ,

which implies that

$$\int_{\mathbb{R}^2} u^2 dx = 1 \text{ and } \lim_{n \to \infty} \int_{\mathbb{R}^2} K(x) u_n^4 dx = \int_{\mathbb{R}^2} K(x) u^4 dx.$$

Then we obtain that  $u \in S$ . Furthermore, according to ([20], Lemma 2.2), we have

$$\int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln |x - y| u^2(x) u^2(y) dx dy \leq \liminf_{n \to \infty} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln |x - y| u_n^2(x) u_n^2(y) dx dy.$$

Together with the weak lower semicontinuity of norm, we then deduce from above that

$$e(a) \leq E_a(u) \leq \liminf_{n \to \infty} E_a(u_n) = e(a),$$

which yields that  $E_a(u) = e(a)$ . This indicates that u is a minimizer of e(a) for  $a \in (0, a^*)$ .

2). Consider the function

$$u_{\tau}(x) = \frac{\tau}{\sqrt{a^*}} Q(\tau x), \quad \tau > 0.$$

Then  $u_{\tau} \in S$  for all  $\tau > 0$ . We deduce from (1.12) that

$$e(a) \leq E_{a}(u_{\tau}) = \frac{\tau^{2}}{4a^{*}} \int_{\mathbb{R}^{2}} \left[ 1 - \frac{a}{a^{*}} K\left(\frac{x}{\tau}\right) \right] Q^{4}(x) dx + \frac{1}{2\tau^{2}a^{*}} \int_{\mathbb{R}^{2}} |x|^{2} Q^{2}(x) dx + \frac{1}{4(a^{*})^{2}} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} |x|^{2} Q^{2}(x) Q^{2}(y) dx dy - \frac{1}{4} \ln \tau.$$
(2.5)

Through (1.4), (1.10), (2.2) and the assumption (1.7), we obtain from (2.5) that

$$e(a) \leq \lim_{\tau \to \infty} E_a(u_{\tau}) = -\infty \text{ for } a > a^*,$$

which implies that there is no minimizer of e(a) and  $e(a) = -\infty$  when  $a > a^*$ . 3). For the case  $a = a^*$ , we infer from (2.5) that

$$e(a) \leq E_{a}(u_{\tau}) = \frac{\tau^{2}}{4a^{*}} \int_{\mathbb{R}^{2}} \left[ 1 - K\left(\frac{x}{\tau}\right) \right] Q^{4}(x) dx + \frac{1}{2\tau^{2}a^{*}} \int_{\mathbb{R}^{2}} |x|^{2} Q^{2}(x) dx + \frac{1}{4\left(a^{*}\right)^{2}} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln|x - y| Q^{2}(x) Q^{2}(y) dx dy - \frac{1}{4} \ln \tau.$$
(2.6)

In virtue of (1.10), we can take  $\delta > 0$  satisfying  $\int_{|x|>\delta} Q^4 dx < \tau^{-2}$ . Hence we get from (1.7) that

$$\frac{\tau^2}{4a^*} \int_{|x|>\delta} \left[ 1 - K\left(\frac{x}{\tau}\right) \right] Q^4(x) dx \le \frac{1}{2a^*}$$

By the assumption that  $1 - K(x) = O(|x|^2)$  as  $x \to 0$ , we have

$$\frac{\tau^2}{4a^*}\int_{|x|\leq\delta}\left[1-K\left(\frac{x}{\tau}\right)\right]Q^4(x)\mathrm{d}x\leq C \text{ as } \tau\to\infty.$$

Therefore, we obtain from (1.4), (1.10), (2.2) and (2.6) that

$$e(a^*) \leq \lim_{\tau \to \infty} E_{a^*}(u_{\tau}) = -\infty,$$

which means that there is no minimizer of  $e(a^*)$  and  $e(a^*) = -\infty$ . In addition, for  $a \in (0, a^*)$ , choosing  $\tau = (a^* - a)^{-\frac{1}{2}}$  in (2.5), we get

$$e(a) \leq \frac{1}{2a^{*}} + \frac{\tau^{2}a}{4(a^{*})^{2}} \int_{\mathbb{R}^{2}} \left[ 1 - K\left(\frac{x}{\tau}\right) \right] Q^{4}(x) dx + \frac{1}{2\tau^{2}a^{*}} \int_{\mathbb{R}^{2}} |x|^{2} Q^{2}(x) dx + \frac{1}{4(a^{*})^{2}} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln|x - y| Q^{2}(x) Q^{2}(y) dx dy - \frac{1}{4} \ln \tau.$$

$$(2.7)$$

One can also obtain from the assumption  $1 - K(x) = O(|x|^2)$  as  $x \to 0$  that

$$\frac{\tau^2 a}{4(a^*)^2} \int_{\mathbb{R}^2} \left[ 1 - K\left(\frac{x}{\tau}\right) \right] Q^4(x) dx \le C \text{ as } a \nearrow a^*.$$

Thus we obtain from (1.4), (1.10), (2.2) and (2.7) that  $\lim_{a \nearrow a^*} e(a) = -\infty$ . This completes the proof of Theorem 1.1.

# 3. Limiting Behavior of Minimizers

In this section, we shall prove Theorem 1.2 on the limiting behavior of positive minimizers for e(a) as  $a \nearrow a^*$ . We first establish some estimates for the positive minimizers of e(a) as  $a \nearrow a^*$ .

**Lemma 3.1.** Assume that  $u_a$  is a positive minimizer of e(a) for  $a \in (0, a^*)$ and  $1 - K(x) = O(|x|^2)$  as  $x \to 0$ . Let

$$\varepsilon_a := \left( \int_{\mathbb{R}^2} \left| \nabla u_a \right|^2 \mathrm{d}x \right)^{-\frac{1}{2}}, \tag{3.1}$$

$$v_a(x) := \varepsilon_a u_a(\varepsilon_a x + x_a) \text{ in } \mathbb{R}^2, \qquad (3.2)$$

where  $x_a$  is a global maximum point of  $u_a$ . Then [(1)]

1)  $\varepsilon_a > 0$  satisfies

$$\varepsilon_a \to 0 \text{ and } \mu_a \varepsilon_a^2 \to -1 \text{ as } a \nearrow a^*;$$
 (3.3)

2) There exists a constant  $\eta > 0$ , independent of  $a \in (0, a^*)$ , such that

$$\int_{B_2(0)} v_a^2(x) \mathrm{d}x \ge \eta \quad \text{as } a \nearrow a^*; \tag{3.4}$$

3)  $v_a$  satisfies

$$v_a(x) \rightarrow \frac{1}{\sqrt{a^*}} Q(|x|) \text{ in } H^1(\mathbb{R}^2) \text{ as } a \nearrow a^*;$$
 (3.5)

4) There exist a large constant R > 0 and a constant C > 0, independent of a, such that

$$\left|v_a(x)\right| \le C \mathrm{e}^{\frac{2|x|}{3}} \text{ for } |x| \ge R \text{ as } a \nearrow a^*.$$
 (3.6)

**Proof.** 1). Through (2.2) and (2.3), we have

$$e(a) = E_a(u_a) \ge \frac{a^* - a}{2a^*} \varepsilon_a^{-2} - C\varepsilon_a^{-1} \ge -C\varepsilon_a^{-1}.$$

Together with the fact  $\lim_{a \nearrow a^*} e(a) = -\infty$  in Theorem 1.1, we obtain that  $\varepsilon_a \to 0$  as  $a \nearrow a^*$ .

By (3.1), we have

$$\varepsilon_{a}^{2}e(a) = \frac{1}{2} + \frac{\varepsilon_{a}^{2}}{2} \int_{\mathbb{R}^{2}} |x|^{2} u_{a}^{2}(x) dx + \frac{\varepsilon_{a}^{2}}{4} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln(1+|x-y|) u_{a}^{2}(x) u_{a}^{2}(y) dxdy - \frac{\varepsilon_{a}^{2}}{4} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln\left(1+\frac{1}{|x-y|}\right) u_{a}^{2}(x) u_{a}^{2}(y) dxdy - \frac{a\varepsilon_{a}^{2}}{4} \int_{\mathbb{R}^{2}} K(x) u_{a}^{4}(x) dx.$$
(3.7)

Since  $\varepsilon_a \to 0$  as  $a \nearrow a^*$ , we derive from (2.2) that

$$0 \le \varepsilon_a^2 \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln\left(1 + \frac{1}{|x - y|}\right) u_a^2(x) u_a^2(y) dx dy \le C\varepsilon_a \to 0 \text{ as } a \nearrow a^*.$$
(3.8)

Note from (2.3) that

$$\frac{1}{2}\left(1-\frac{a\varepsilon_{a}^{2}}{2}\int_{\mathbb{R}^{2}}K(x)u_{a}^{4}(x)\mathrm{d}x\right)\geq0.$$
(3.9)

Hence we deduce from (3.7)-(3.9) that  $\liminf_{a \nearrow a^*} \varepsilon_a^2 e(a) \ge 0$ . Using the fact that  $\lim_{a \nearrow a^*} e(a) = -\infty$  again, we have  $\limsup_{a \nearrow a^*} \varepsilon_a^2 e(a)^* \le 0$ . Therefore, we conclude that  $\lim_{a \nearrow a^*} \varepsilon_a^2 e(a) = 0.$  (3.10)

Furthermore, one can obtain from (3.7)-(3.10) that

$$\lim_{a \nearrow_{a}^{*}} \varepsilon_{a}^{2} \int_{\mathbb{R}^{2}} K(x) u_{a}^{4} dx = \frac{2}{a^{*}}, \quad \lim_{a \nearrow_{a}^{*}} \varepsilon_{a}^{2} \int_{\mathbb{R}^{2}} |x|^{2} u_{a}^{2} dx = 0, \quad (3.11)$$

$$\lim_{a \nearrow a^*} \mathcal{E}_a^2 \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln(1 + |x - y|) u_a^2(x) u_a^2(y) dx dy = 0.$$
(3.12)

Note from (1.14) that

$$\mu_{a}\varepsilon_{a}^{2} = 2\varepsilon_{a}^{2}e(a) + \frac{\varepsilon_{a}^{2}}{2}\int_{\mathbb{R}^{2}}\int_{\mathbb{R}^{2}}\ln|x-y|u_{a}^{2}(x)u_{a}^{2}(y)dxdy$$
  
$$-\frac{a\varepsilon_{a}^{2}}{2}\int_{\mathbb{R}^{2}}K(x)u_{a}^{4}(x)dx.$$
(3.13)

Together with (3.8) and (3.10)-(3.12), we conclude from (3.13) that  $\mu_a \varepsilon_a^2 \rightarrow -1$  as  $a \nearrow a^*$ .

2). Due to (1.13) and (3.2), we see that  $v_a$  satisfies

$$-\Delta v_a + \varepsilon_a^2 \left| \varepsilon_a x + x_a \right|^2 v_a + \varepsilon_a^2 \left( \int_{\mathbb{R}^2} \ln \left| x - y \right| v_a^2 \left( y \right) dy \right) v_a + \varepsilon_a^2 \ln \varepsilon_a v_a$$
  
=  $\varepsilon_a^2 \mu_a v_a + a K \left( \varepsilon_a x + x_a \right) v_a^3$  in  $\mathbb{R}^2$ . (3.14)

We use  $\|\cdot\|$  to denote the standard norm on  $H^1(\mathbb{R}^2)$ . Note that

$$\|v_a\|^2 = \varepsilon_a^2 \int_{\mathbb{R}^2} |\nabla u_a|^2 \, \mathrm{d}x + \int_{\mathbb{R}^2} u_a^2 \, \mathrm{d}x = 2.$$
(3.15)

There exists a constant C > 0 such that for any  $x \in \mathbb{R}^2$  and  $a \in (0, a^*)$ ,

$$\begin{split} &\int_{\mathbb{R}^{2}} \ln \left( 1 + \frac{1}{|x - y|} \right) v_{a}^{2}(y) \, \mathrm{d}y \\ &\leq \int_{|x - y| < 1} \frac{v_{a}^{2}(y)}{|x - y|} \, \mathrm{d}y + \int_{|x - y| \geq 1} \frac{v_{a}^{2}(y)}{|x - y|} \, \mathrm{d}y \\ &\leq \left( \int_{|x - y| < 1} \frac{1}{|x - y|^{\frac{3}{2}}} \, \mathrm{d}y \right)^{\frac{2}{3}} \left( \int_{|x - y| < 1} v_{a}^{6}(y) \, \mathrm{d}y \right)^{\frac{1}{3}} + \int_{|x - y| \geq 1} v_{a}^{2}(y) \, \mathrm{d}y \\ &\leq C \left\| v_{a} \right\|^{2} \leq C, \end{split}$$
(3.16)

Thus we infer from (1.7), (3.3), (3.14) and (3.16) that

$$-\Delta v_a + \frac{5}{9} v_a - a^* v_a^3 \le 0 \text{ in } \mathbb{R}^2 \text{ as } a \nearrow a^*.$$
(3.17)

Since  $x_a$  is a maximum point of  $u_a$ , the origin is a maximum point of  $v_a$  for  $a \in (0, a^*)$ , which illustrates that  $-\Delta v_a(0) \ge 0$  for  $a \in (0, a^*)$ . Thus we get from (3.17) that there exists some constant  $\beta > 0$ , independent of a, such that  $v_a(0) \ge \beta > 0$  as  $a \nearrow a^*$ . Applying the De Giorgi-Nash-Moser theory [25], we derive from (3.17) that there exists a constant C > 0 such that

$$\left(\int_{B_2(0)} v_a^2 dx\right)^{\frac{1}{2}} \ge C \max_{x \in B_1(0)} v_a \ge C\beta := \sqrt{\eta} > 0 \text{ as } a \nearrow a^*.$$

3). In view of (3.15), up to a subsequence if necessary, there exists a function  $v_0 \in H^1(\mathbb{R}^2)$  such that  $v_a \rightharpoonup v_0$  in  $H^1(\mathbb{R}^2)$ ,  $v_a \rightarrow v_0$  in  $L^p_{loc}(\mathbb{R}^2)$  for  $p \in [2,\infty)$ , and  $v_a \rightarrow v_0$  almost everywhere in  $\mathbb{R}^2$  as  $a \nearrow a^*$ . Furthermore, we get  $v_0 \neq 0$  from (3.4). Let o(1) denote the infinitesimal quantities as  $a \nearrow a^*$ . Based on the Brézis-Lieb lemma (cf. [26]), we obtain that as  $a \nearrow a^*$ ,

$$1 = \|v_a\|_2^2 = \|v_0\|_2^2 + \|v_a - v_0\|_2^2 + o(1),$$
$$\|K^{\frac{1}{4}}(\varepsilon_a x + x_a)v_a\|_4^4 = \|K^{\frac{1}{4}}(\varepsilon_a x + x_a)v_0\|_4^4 + \|K^{\frac{1}{4}}(\varepsilon_a x + x_a)(v_a - v_0)\|_4^4 + o(1),$$

and

$$\mathbf{I} = \|\nabla v_a\|_2^2 = \|\nabla v_0\|_2^2 + \|\nabla v_a - \nabla v_0\|_2^2 + o(1).$$

Together with (1.7), (1.11) and (3.11), it yields that

$$\begin{split} 0 &= \lim_{a \nearrow a^{*}} \left( \int_{\mathbb{R}^{2}} |\nabla v_{a}|^{2} dx - \frac{a}{2} \int_{\mathbb{R}^{2}} K\left(\varepsilon_{a} x + x_{a}\right) v_{a}^{4} dx \right) \\ &= \int_{\mathbb{R}^{2}} |\nabla v_{0}|^{2} dx - \lim_{a \nearrow a^{*}} \frac{a}{2} \int_{\mathbb{R}^{2}} K\left(\varepsilon_{a} x + x_{a}\right) v_{0}^{4} dx \\ &+ \lim_{a \nearrow a^{*}} \left( \int_{\mathbb{R}^{2}} |\nabla v_{a} - \nabla v_{0}|^{2} dx - \frac{a}{2} \int_{\mathbb{R}^{2}} K\left(\varepsilon_{a} x + x_{a}\right) |v_{a} - v_{0}|^{4} dx \right) \\ &\geq \frac{a^{*}}{2} \left( \left\| v_{0} \right\|_{2}^{-2} - 1 \right) \int_{\mathbb{R}^{2}} v_{0}^{4} dx + \lim_{a \nearrow a^{*}} \left( \int_{\mathbb{R}^{2}} |\nabla v_{a} - \nabla v_{0}|^{2} dx - \frac{a}{2} \int_{\mathbb{R}^{2}} |v_{a} - v_{0}|^{4} dx \right) \\ &\geq \lim_{a \nearrow a^{*}} \left( 1 - \int_{\mathbb{R}^{2}} |v_{a} - v_{0}|^{2} dx \right) \int_{\mathbb{R}^{2}} |\nabla v_{a} - \nabla v_{0}|^{2} dx \geq 0. \end{split}$$

$$(3.18)$$

Therefore, we conclude from (3.18) that

$$\|v_0\|_2 = 1$$
 and  $\int_{\mathbb{R}^2} |\nabla v_a - \nabla v_0|^2 dx \to 0$  as  $a \nearrow a^*$ ,

which further imply that

$$v_a \rightarrow v_0$$
 in  $H^1(\mathbb{R}^2)$  as  $a \nearrow a^*$ .

Additionally, the first equality of (3.18) yields that

$$\int_{\mathbb{R}^{2}} |\nabla v_{0}|^{2} dx = \frac{a^{*}}{2} \lim_{a \nearrow a^{*}} K(x_{a}) \int_{\mathbb{R}^{2}} v_{0}^{4} dx.$$

Thus we derive from the Lagrange multiplier rule that  $v_0$  satisfies

$$-\Delta v_0 + v_0 - a^* \lim_{a \nearrow a^*} K(x_a) v_0^3 = 0 \text{ in } \mathbb{R}^2.$$

The strong maximum principle implies that  $v_0 > 0$  in  $\mathbb{R}^2$ . Through a simple scaling, the uniqueness (up to translations) of the positive solution of (1.9) ensure that there exists a point  $y_0 \in \mathbb{R}^2$  such that

$$v_0(x) = \left(a^* \lim_{a \nearrow a^*} K(x_a)\right)^{-\frac{1}{2}} Q(|x - y_0|).$$

It follows from  $||v_0||_2 = 1$  that  $\lim_{a \neq a^*} K(x_a) = 1$ . Since the origin is a global maximum point of  $v_a$ , it is also a global maximum point of  $v_0$ . This indicates that  $y_0 = 0$ . Hence we get

$$v_a(x) \rightarrow \frac{1}{\sqrt{a^*}} Q(|x|) \text{ in } H^1(\mathbb{R}^2) \text{ as } a \nearrow a^*.$$

This convergence is independent of the choice of subsequences and holds true for the whole sequence as well.

4). Using the De Giorgi-Nash-Moser theory (cf. [25]), we derive from (3.15) and (3.17) that

$$\max_{e \in B_{1}(\xi)} v_{a} \leq C \left( \int_{B_{2}(\xi)} v_{a}^{2} \mathrm{d}x \right)^{\frac{1}{2}} \text{ for any } \xi \in \mathbb{R}^{2},$$

where C > 0 is a constant independent of a and  $\xi$ . Together with (3.5) and

(3.15), we get that  $\{v_a\}$  is bounded uniformly in  $L^{\infty}(\mathbb{R}^2)$  and

$$v_a(x) \to 0 \text{ as } |x| \to \infty \text{ uniformly in } a \nearrow a^*,$$
 (3.19)

Combining (3.19) with (3.17) then yields that there exists a large constant R > 0 such that

$$-\Delta v_a + \frac{4}{9}v_a \le 0 \text{ for } |x| \ge R \text{ uniformly in } a \nearrow a^*.$$
(3.20)

By applying the comparison principle to (3.20), we can conclude that there exists a positive constant C > 0 such that

$$|v_a(x)| \le C \mathrm{e}^{-\frac{2|x|}{3}}$$
 for  $|x| \ge R$  uniformly in  $a \nearrow a^*$ . (3.21)

Thus we complete the proof of Lemma 3.1.

Now we prove the refined limiting behavior of positive minimizers of e(a) in X as  $a \nearrow a^*$ .

**Proof of Theorem 1.2.** Using the exponential decays (1.10) and (3.6), we get that for any  $\epsilon > 0$ , there exists a constant R > 0 such that

$$2\int_{B_{R}^{c}}|x|^{2}v_{a}^{2}(x)\,\mathrm{d}x+2\int_{B_{R}^{c}}|x|^{2}\frac{Q^{2}(x)}{a^{*}}\,\mathrm{d}x<\frac{\epsilon}{2}.$$

Combining this with (3.5) we obtain that

$$\begin{split} &\int_{\mathbb{R}^{2}} |x|^{2} \left( v_{a}\left(x\right) - \frac{Q\left(x\right)}{\sqrt{a^{*}}} \right)^{2} dx \\ &= \int_{B_{R}} |x|^{2} \left( v_{a}\left(x\right) - \frac{Q\left(x\right)}{\sqrt{a^{*}}} \right)^{2} dx + \int_{B_{R}^{c}} |x|^{2} \left( v_{a}\left(x\right) - \frac{Q\left(x\right)}{\sqrt{a^{*}}} \right)^{2} dx \\ &\leq |R|^{2} \int_{B_{R}} \left( v_{a}\left(x\right) - \frac{Q\left(x\right)}{\sqrt{a^{*}}} \right)^{2} dx + 2 \int_{B_{R}^{c}} |x|^{2} v_{a}^{2}\left(x\right) dx + 2 \int_{B_{R}^{c}} |x|^{2} \frac{Q^{2}\left(x\right)}{a^{*}} dx \\ &< \epsilon \text{ as } a \nearrow a^{*}. \end{split}$$

Together with (3.5), we can indicate that  $v_a(x) \to \frac{Q}{\sqrt{a^*}}$  in X as  $a \nearrow a^*$ .

In older to complete the proof of Theorem 1.2, we next need to prove that

$$\varepsilon_a = 2\sqrt{\frac{a^* - a}{a^*}} \left(1 + o\left(1\right)\right) \text{ as } a \nearrow a^*.$$
(3.22)

Firstly, we derive the upper estimate of e(a) as  $a \nearrow a^*$ . Setting

$$\tau = \left[\frac{a^*}{4(a^*-a)}\right]^{\frac{1}{2}} > 0$$

into (2.5), we deduce that

$$e(a) \leq \frac{1}{8} - \frac{1}{8} \ln a^* + \frac{1}{8} \ln 4 \left( a^* - a \right) + \frac{1}{4 \left( a^* \right)^2} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln |x - y| Q^2(x) Q^2(y) dx dy + o(1) \text{ as } a \nearrow a^*.$$
(3.23)

$$\begin{split} & \left| \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| v_{a}^{2}(x) v_{a}^{2}(y) dx dy - \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| \frac{Q^{2}(x)}{a^{*}} \frac{Q^{2}(y)}{a^{*}} dx dy \right| \\ &= \left| \left( \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| v_{a}^{2}(x) v_{a}^{2}(y) dx dy - \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| \frac{Q^{2}(x)}{a^{*}} v_{a}^{2}(y) dx dy \right) \right| \\ &- \left( \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| \frac{Q^{2}(x)}{a^{*}} \frac{Q^{2}(y)}{a^{*}} dx dy - \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| \frac{Q^{2}(x)}{a^{*}} v_{a}^{2}(y) dx dy \right) \right| \\ &\leq \left| \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| \left( v_{a}^{2}(x) - \frac{Q^{2}(x)}{a^{*}} \right) v_{a}^{2}(y) dx dy \right| \\ &+ \left| \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| \frac{Q^{2}(x)}{a^{*}} \left( v_{a}^{2}(y) - \frac{Q^{2}(y)}{a^{*}} \right) dx dy \right| \\ &\leq \int_{\mathbb{R}^{2}} \left| x \right| \left| v_{a}^{2}(x) - \frac{Q^{2}(x)}{a^{*}} \right| dx + \int_{\mathbb{R}^{2}} \left| v_{a}^{2}(x) - \frac{Q^{2}(x)}{a^{*}} \right| dx dy \right| \\ &\leq \int_{\mathbb{R}^{2}} \left| x \right| \left| v_{a}^{2}(x) - \frac{Q^{2}(x)}{a^{*}} \right| dx + \int_{\mathbb{R}^{2}} \left| v_{a}^{2}(x) - \frac{Q^{2}(x)}{a^{*}} \right| dx dy \right| \\ &+ \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \frac{1}{|x - y|} \frac{Q^{2}(x)}{a^{*}} dx \int_{\mathbb{R}^{2}} \left| v_{a}^{2}(y) - \frac{Q^{2}(y)}{a^{*}} \right| dy + a^{*} \int_{\mathbb{R}^{2}} \left| y \right| \left| v_{a}^{2}(y) - \frac{Q^{2}(y)}{a^{*}} \right| dy \\ &+ \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \frac{1}{|x - y|} \frac{Q^{2}(x)}{a^{*}} \left| v_{a}^{2}(y) - \frac{Q^{2}(y)}{a^{*}} \right| dx dy \to 0 \quad \text{as } a \nearrow^{a}. \end{split}$$

We now give the lower estimate of e(a) as  $a \nearrow a^*$ . It follows from (1.11), (3.5) and (3.24) that

$$e(a) = E(u_{a})$$

$$= \frac{1}{2}\varepsilon_{a}^{-2} \left( \int_{\mathbb{R}^{2}} |\nabla v_{a}|^{2} dx - \frac{a^{*}}{2} \int_{\mathbb{R}^{2}} K(\varepsilon_{a}x + x_{a})v_{a}^{4} dx \right) + \frac{1}{2} \int_{\mathbb{R}^{2}} |\varepsilon_{a}x + x_{a}|^{2} v_{a}^{2}(x) dx$$

$$+ \frac{1}{4} \ln \varepsilon_{a} + \frac{1}{4} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| v_{a}^{2}(x) v_{a}^{2}(y) dx dy$$

$$+ \frac{1}{4} (a^{*} - a) \varepsilon_{a}^{-2} \int_{\mathbb{R}^{2}} K(\varepsilon_{a}x + x_{a}) v_{a}^{4} dx$$

$$\geq \frac{1}{4} (a^{*} - a) \varepsilon_{a}^{-2} \int_{\mathbb{R}^{2}} v_{a}^{4} dx + \frac{1}{4} \ln \varepsilon_{a} + \frac{1}{4} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| v_{a}^{2}(x) v_{a}^{2}(y) dx dy$$

$$= \frac{a^{*} - a}{2a^{*}} (1 + o(1)) \varepsilon_{a}^{-2} + \frac{1}{4} \ln \varepsilon_{a}$$

$$+ \frac{1}{4(a^{*})^{2}} (1 + o(1)) \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| Q^{2}(x) Q^{2}(y) dx dy$$

$$\geq \frac{1}{8} + \frac{1}{8} \ln 4(a^{*} - a) - \frac{1}{8} \ln a^{*}$$

$$+ \frac{1}{4(a^{*})^{2}} \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} \ln |x - y| Q^{2}(x) Q^{2}(y) dx dy + o(1) \text{ as } a \nearrow a^{*},$$

where the identity in the above inequality is achieved at  $\varepsilon_a > 0$  satisfying (3.22),

*i.e.*,  $\varepsilon_a = 2\sqrt{\frac{a^*-a}{a^*}}(1+o(1))$  as  $a \nearrow a^*$ . We now conclude from (3.23) and (3.25)

that

$$e(a) \approx \frac{1}{8} + \frac{1}{8} \ln 4(a^* - a) - \frac{1}{8} \ln a^* + \frac{1}{4(a^*)^2} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \ln |x - y| Q^2(x) Q^2(y) dx dy \text{ as } a \nearrow a^*$$

and  $\varepsilon_a > 0$  satisfies (3.22). Moreover, because  $v_a \to \frac{Q}{\sqrt{a^*}}$  in X as  $a \nearrow a^*$ ,

we obtain from Lemma 3.1 that

$$\lim_{a \neq a^{*}} 2\sqrt{\frac{a^{*} - a}{a^{*}}} u_{a} \left( 2\sqrt{\frac{a^{*} - a}{a^{*}}} x + x_{a} \right) = \frac{Q(x)}{\sqrt{a^{*}}} \text{ in } X.$$

This completes the proof of Theorem 1.2.

Through relevant proofs and discussions, the existence of minimizers for e(a) and the refined limiting behavior of positive minimizers for e(a) have been analyzed as  $a \nearrow a^*$ . These mathematical conclusions provide a theoretical basis for the stability of complex quantum systems and physical phenomena under extreme conditions. In future research, we can discuss the local uniqueness of constraint minimizers as  $a \nearrow a^*$  to refine the results.

## **Conflicts of Interest**

The authors declare no conflicts of interest.

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